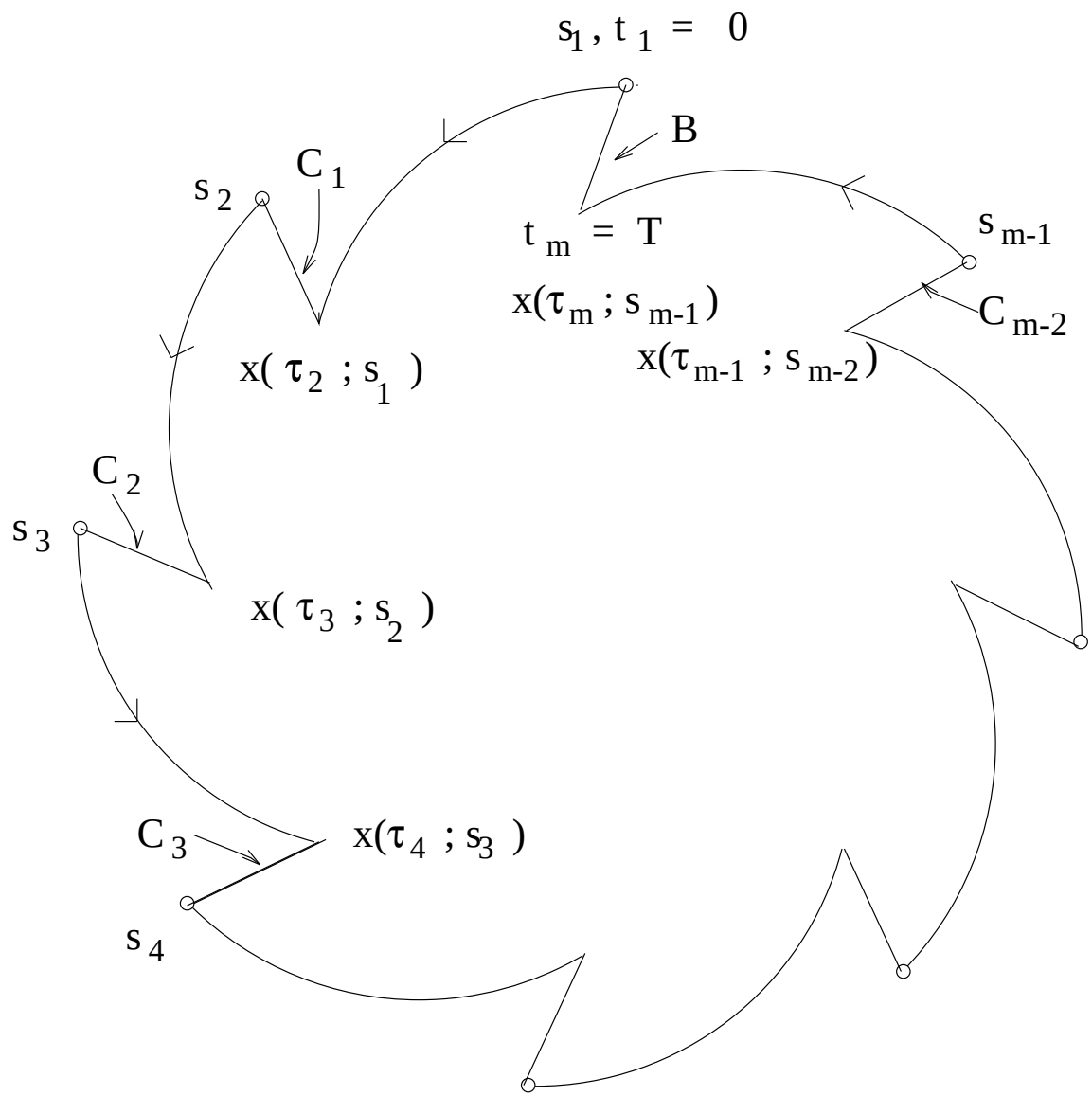
$s_1, t_1 = 0$
B
C_1
s_2
$t_m = T$
s_{m-1}
$x(\tau_m ; s_{m-1})$
C_{m-2}
$x(\tau_2 ; s_1)$
$x(\tau_{m-1} ; s_{m-2})$
C_2
s_3
$x(\tau_3 ; s_2)$
C_3
$x(\tau_4 ; s_3)$
s_4